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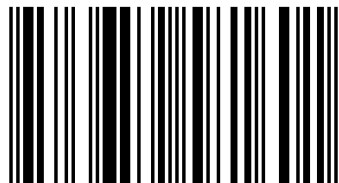
Mohammed Elmardi Osama



Osama Mohammed Elmardi received his Diploma degree in mechanical engineering from Mechanical Engineering College, Atbara, Sudan in 1990. He also received a Bachelor degree in mechanical engineering from Sudan University of Science and Technology – College of Engineering in 1998, and a Master degree in solid mechanics from Nile valley university.

Further Experimental Research Work On Water Current Turbines

Case Study on Atbara Water Current Turbine



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Further Experimental Research Work on Water Current
Turbines

Osama Mohammed Elmardi Suleiman

October 2010

Dedication

In the name of Allah, the merciful, the compassionate

All praise is due to Allah and blessings and peace is upon his messenger and servant, Mohammed, and upon his family and companions and whoever follows his guidance until the day of resurrection.

To the memory of my mother Khadra Dirar Taha, my father Mohammed Elmardi, and my aunt Zaafaran who taught me the greatest value of hard work and encouraged me in all my endeavours.

To my first wife Nawal Abbas and my beautiful three daughters Roa, Rawan and Aya whose love, patience and silence are my shelter whenever it gets hard.

To my second wife Limya Abdullah whose love and supplication to Allah were and will always be the momentum that boosts me through the rough road of research.

This book is dedicated mainly to undergraduate engineering students, especially mechanical engineering students where most of the applications are presented in the mechanical engineering field.

Finally, may Allah accept this humble work and i hope it will be beneficial to its readers.

Acknowledgement

I am grateful and deeply indebted to Professor Physicist Dr. M.H.A. Sinada for close supervision, consultation and constructive criticism, without which this work would not have been accomplished.

I am also indebted to many people. Published texts in fluid mechanics and hydraulic machinery have been contributed to the author's thinking. Members of Mechanical Engineering Department at Faculty of Engineering and Technology have served to sharpen and refine the treatment of my topics. The author is extremely grateful to them for constructive criticisms and valuable suggestions.

The author would like to acknowledge with deep thanks and gratitude the moral and financial support extended to him by Nile Valley University via its Faculty of Engineering and Technology despite its financial hardships.

My thanks are extended to Professor Mahmoud Yassin Osman for giving me his great experience in writing reports, researches and books according to the standard format, and also for revising several times the manuscript of the present book.

Special gratitude is due to Professor Mohammed Ibrahim Shukri for continuous follow up step by step the completion of this book and the greatest advice he has given to me in writing sequentially the various chapters of this book.

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Finally i would like to acknowledge the generous assistance of the staff at different levels working in the industrial liaison and consultancy unit, Atbara.

Abstract

The motivation that led to the writing of the present book is the necessity to exploit the high velocity energy of River Nile that obtained when River Atbara meets River Nile in Atbara town which is located in River Nile State. At the junction of the two rivers high velocity energy is gained, and therefore, a suitable energy converter is needed to utilize this abundant energy.

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Contents

Description	Page	
Acknowledgement	i	
Abstract	ii	
Contents	iii	
List of figures	v	
List of tables	vi	
Preface	vii	
Chapter One	Introduction	
	1.1 Historical background	1
	1.2 Water – current energy	2
	1.3 Atbara Water – current turbine	3
Chapter Two	Aerofoil theorem	
	2.1 Aerofoil definitions	5
	2.2 Aerofoil terminologies	5
	2.3 Geometrical parameters	6
	2.4 Aerofoil types	7
	2.5 Generation of lift and drag	7
Chapter Three	Model design and testing procedures	
	3.1 Model design	11
	3.2 Testing procedures	13
Chapter Four	Discussion of results	
	4.1 Readings	18
	4.2 Sample of calculations	18
	4.3 Results	20
	4.4 Comments on graphs and results	20

	analysis	
Chapter Five	Conclusions and recommendations	
	5.1 Conclusions	29
	5.2 Recommendations	30
References		31

List of Figures

Serial	Description	Page
2.1	Asymmetric aerofoil	9
2.2	Symmetric aerofoil	9
2.3	Two types of aerofoidal section profiles	10
2.4	Variation of C_L and C_D with α for a typical aerofoil	10
3.1	The straight – cambered aerofoil drawn in full – size dimensions	15
3.2	The cambered – cambered aerofoil drawn in full – size dimensions	15
3.3	The holding mechanism of the water – current turbine model	16
3.4	The full – size water current turbine (Atbara water current turbine)	17
4.1	Efficiency against angle of incidence of straight – cambered aerofoil	25
4.2	Coefficient of lift against angle of incidence of straight – cambered aerofoil	26
4.3	Efficiency against angle of incidence of cambered – cambered aerofoil	27
4.4	Coefficient of lift against angle of incidence of cambered – cambered aerofoil	28

List of Tables

Serial	Description	Page
4.1	Readings of the straight – cambered aerofoil	21
4.2	Readings of the cambered – cambered aerofoil	22
4.3	Calculated results of the straight – cambered aerofoil	23
4.4	Calculated results of the cambered – cambered aerofoil	24

Preface

This book was originally prepared in 1998 and updated recently in 2010. The concept of this book was initiated as a result of the continuing and increasing demand for small irrigation units that could be installed and operated on the River Nile banks in Northern and River Nile States in Sudan.

Experiments were executed on two types of turbine blade's section profiles, i.e. Straight – cambered section profile and cambered – cambered section profile for the comparison between these two types from the point of view of their performance and therefore, to differentiate between them so as to determine their practical usage.

The material presented is intended to serve as a basis for study of the fundamentals of aerofoil theory and several branches of fluid mechanics, and hydraulic machinery. Chapter one of this book constitutes an introduction which introduces a historical background of exploiting water current energy in power generating plants, and at the end of this chapter the basic objectives of the present study are stated. Chapter two explains the classical aerofoil theory and some definitions of aerofoidal sections terminologies. Chapter three deals with the design of the proposed model, and the procedures used for testing it. Chapter four illustrates the readings obtained and the corresponding results through tables, graphs and samples of calculation. Chapter five includes conclusions and recommendations, which justifies the use of such type of aerofoidal section, and the development and improvement of the design.

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Chapter One

Introduction

1.1 Historical Background:

The increased consumption of energy resources year after another, has been threatening our globe since the inception of the industrial revolution before three quarters century. The invention of engines and machines has been followed by drilling the ground searching for oil and other mineral resources. This eager and crazy race of trying to possess the available forms of energy by any means, and to convert it into products and/or services for the welfare of human beings encourages the scientists and researchers to do their best in order to save the world limited resources from replenishment. The scientific research was therefore being directed towards finding other resources of energy which must be continuous and eternal i.e. renewable energy like solar, wind, biological, gas, underground latent heat, and water-current energy. These forms of energy can be utilized with very small or approximately no running cost to solve completely or partially the energy problems in many countries throughout the world. But now the problem is the elevated initial cost of constructing the converting units which is capable of changing these raw energy sources into useful forms.

The utilization of water-current power was started in the first century, where the river's water-current was used to power under-water mill for crushing corn. The first mill was used in the fourth century in the middle-east with a horizontal shaft, and then it was developed to have a vertical shaft. At the beginning of the industrial revolution, the mill was used in Europe and the United States for the purpose of pumping water and wood cutting. The less well – known method of extracting energy from tidal and other flows is to convert the kinetic or velocity energy of moving water directly to mechanical shaft without otherwise interrupting the natural flow in a manner similar to a wind turbine. This idea is not completely new as it has been investigated by Reading University in the U.K. in 1979 [1], by Davis in

Canada [2] and by Hilton in Australia at about the same period [3]. It was in use in Africa on a small scale in the early 1980s to extract energy from river currents [1]. But the idea of using current flow on a large scale is new. Even as recently as 1991 a complete book on tidal energy made no mention of the concept [4]. It is only now that this concept is being explored for larger scale use [2, 5, 6, 7, 8, 9, and 10].

Direct conversion of kinetic energy by a turbine in open flow harnesses less of the total available energy in a tidal flow in an estuary than could be extracted by damming the whole estuary. However, direct conversion has several advantages:

1. The capital cost of civil works is eliminated.
2. Disruption to ecosystems and boating traffic is minimized.
3. Ocean currents, wind induced currents and river flows as well as tidal flows can be used.

Here in Sudan, all the above-mentioned types of renewable energy are widely and abundantly found, but the appropriate technology of exploiting them has not yet been introduced.

1.2 Water – Current energy:

The natural power of a running river or a stream has been of interest for electricity production for many years. The technology of small scale hydropower is diverse, and different concepts have been developed and tried out [11 – 17], i.e. water current turbines with a unit power output of about 0.5–5kw. These turbines are supposed to be used for domestic electricity applications such as lighting, battery charging, and small refrigerators and also for small pumping units. The units are small, cheap and often owned, installed and used by a single family.

Water current turbines have received a growing interest in many parts of the globe. Two main areas where these turbines can be used for pumping and/or power generation purposes are tidal currents and river streams. This book will focus on water current turbines for river applications. These turbines generate power from the kinetic energy of a flowing stream of water without the use of a

dam. Water current turbines can be installed in any flow with a velocity greater than 0.5m/s [18, 19]. Because of low investment costs and maintenance fees, this technology is cost effective in comparison to other technologies. This kind of small scale hydropower is considered environmentally friendly, meaning that there are no toxic emissions as that exhausted from diesel engines. Small scale water current turbines can be a solution for pumping purposes and power supply in remote areas [20].

The kinetic energy of water-currents of river is a reliable energy source for operating mills, pumps, electrical generators etc... A current speed of (1 m/s) represents an energy flux of 500 watts per (m^2) of river cross-section. Attempts to utilize this energy for pumping purposes were initiated in 1975 at Mechanical Engineering College Atbara (MECA) through students' final year project. The idea of this project was to design and create experimental data of a piston pump driven by a floating water wheel. After several attempts during the last twenty years, a successful approach has been reached, where a completely submerged three- blades turbine driving ordinary centrifugal pump through speed increasing transmission is used, which is known afterwards as water - current turbine.

1.3 Atbara Water – Current Turbine:

The water current turbine which was designed and constructed in the Faculty of Engineering and Technology, Nile Valley University - Atbara is an energy converter, used to convert the kinetic energy of water currents into mechanical energy, which is in turn used to drive a centrifugal pump for irrigation purposes. This unit is composed of a rotor with three blades coupled to a shaft which transmits power to a centrifugal pump through a simple transmission system "pulleys and belts" as shown in fig. (3.4). Water is pumped from the river to the irrigation canal on the river bank through a rigid pipeline which also acts as an access walkway to the machine. All this arrangement is carried on buoyant barrels closed at both ends and connected by steel frame or bed. This unit develops about 1000 watts with an overall efficiency of 24 percent and costs about 6 million

Sudanese pounds (i.e. fifteen thousand pounds in today's price), the initial cost of the construction of this unit is relatively high compared with Lister diesel engine for the same output power. This induces the idea of this project in order to improve the ratio of power developed per initial cost through modifying the previous design of the whole system using the following procedures:

There are two areas which can be investigated to comply with the modified objectives.

- i. To establish data of performance concerning Atbara water-current turbine for the first time i.e. to determine speed and torque for different angles of attack for the two proposed types of aerofoils, the straight – cambered and the cambered – cambered aerofoils.
- ii. To propose some changes in Atbara water-current turbine in order to improve the existing designs.

Chapter Two

Aerofoil Theorem

2.1 Aerofoil Definitions:

An aerofoil is a streamlined body designed to produce lift with minimum drag. In a streamlined body, immersed in a flowing fluid, separation is delayed till near the rear. This will decrease the drag on the streamline body to a minimum value. The drag on a streamline body can be as low as $1/15$ of that on a cylinder of the same thickness.

The most important feature is the slowly tapering tail. This is the reason why streamlining of a railway engine with a train behind it makes only marginal difference. On the other hand, it is essential to their performance that the wings and fuselage of an aeroplane and the parts of a sub-marine should have streamlined profiles. It is also apparent that the shapes shown in figs. (2.1) and (2.2) resemble the shape of many marine creatures i.e. fishes, dolphins etc... (Refer to references [21 – 32]).

2.2 Aerofoil Terminologies:

Fig (2.1) shows a typical aerofoil section and some of the terms relating to it. These terms are as follows:

2.2.1 Leading Edge:

It is the edge which faces the direction of flow firstly and sometimes referred to as a nose.

2.2.2 Trailing Edge:

It is the far edge of the rear edge of an aerofoil.

2.2.3 Chord:

It is the distance between the leading edge and the trailing edge points.

2.2.4 Chord Line:

It is the straight line drawn to connect the two edges together.

2.2.5 Camber Line:

It is the line connecting the two edges so that it should pass through the centroid of an aerofoil.

2.2.6 Angle of Incidence:

It is the angle at which the chord line of an aerofoil makes with the direction of flow and sometimes referred to as the angle of attack.

2.3 Geometrical Parameters:

The characteristics of any aerofoil section are largely determined by some geometrical parameters. These parameters are:

2.3.1 (t/c) Ratio:

It is the ratio between the maximum thickness (t) and the chord line (C).

2.3.2 (x/c) Ratio:

It is the ratio between the position of the maximum thickness of the nose and the chord length.

2.3.3 Percentage Camber:

It is the ratio between the maximum camber and the chord length (as a percentage).

2.3.4 Percentage Nose Radius:

It is the nose radius of curvature as a percentage of the chord length.

2.3.5 Trailing Edge Angle:

It is the angle between the upper and lower surfaces at the trailing edge.

2.4 Aerofoil Types:

Aerofoils are generally classified into two types; symmetric and asymmetric aerofoils.

2.4.1 Symmetric Aerofoils:

The main feature in this type of aerofoils is that the camber line coincides with the chord line as shown in fig. (2.2). These aerofoils are rarely used in practice since higher values of lift and lower values of drag can still be obtained by other types of aerofoils.

2.4.2 Asymmetric Aerofoils:

The ratio between lift and drag (L/D) can be improved by using asymmetric aerofoils. In these aerofoils the camber line doesn't coincide with the chord line as shown in fig. (2.1), the simplest form of asymmetric aerofoils is called cambered aerofoils in which the camber line is made into a circular arc. In cambered aerofoils both faces can be made curved in one direction or the top face curved while the bottom face is straight as shown in fig. (2.3) {(a) and (b)}.

2.5 Generation of Lift and Drag:

If an aerofoil is placed in a stream of a flowing fluid, the streamlines around the aerofoil will be deflected resulting in a decrease in pressure on the upper surface and an increase in pressure on the lower surface. Due to this difference in pressure a force is generated which may be resolved into two components: a component parallel to the direction of flow giving the drag force (D), and a second component normal to the main stream giving the lift force (L) as shown in fig. (2.1), both lift and drag forces are substituted in terms of the maximum dynamic force (\hat{F}) which is given by the formula:

$$\hat{F} = \frac{1}{2} \ell u_0^2 A \quad (\text{N}) \quad (2.1)$$

Where; ℓ = water density in (kg/m³).

u_o = relative velocity between the flowing fluid and the body in (m/s).

A = projected area on the chord line in (m^2).

The lift force is:

$$L = \frac{1}{2} C_L \rho u_o^2 A \quad (\text{N}) \quad (2.2)$$

The drag force is:

$$D = \frac{1}{2} C_D \rho u_o^2 A \quad (\text{N}) \quad (2.3)$$

Where; C_L = Coefficient of lift.

C_D = coefficient of drag.

The ratio (L/D) or $\{C_L/C_D\}$ is very important and it depends on the angle of incidence (α) and other geometrical parameters.

The best angle of incidence is one which gives maximum value of $\{C_L/C_D\}$. With increase of angle of incidence from zero, the suction (negative pressure) increases over the upper surface, particularly towards the leading edge and with it the lift increases. However, at a sufficiently high incidence the adverse pressure gradient following the peak approaches a value for which boundary layer separation develops. With further increase of incidence the flow separation rapidly spreads over the upper surface, and the peak suction falls. In this case over the region of the separated flow the pressure becomes more nearly constant over the surface whilst the trailing edge pressure and the lift fall. The wing is then said to be stalled.

The performance of any aerofoil blade can be drawn in a graph showing the variations of lift coefficient (C_L) and drag coefficient (C_D) with the incidence angle (α). Fig. (2.4) shows atypical variations of coefficient of lift (C_L) and coefficient of drag (C_D) with angles of incidence (α).

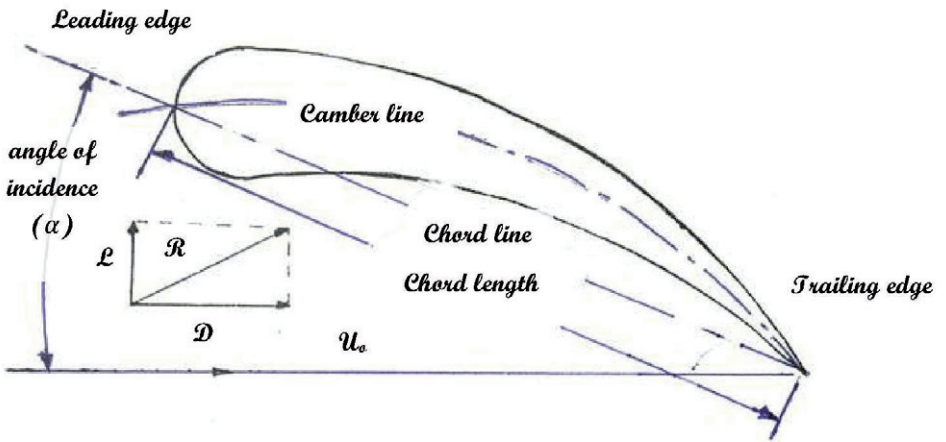


Fig. (2.1) Asymmetric Aerofoil

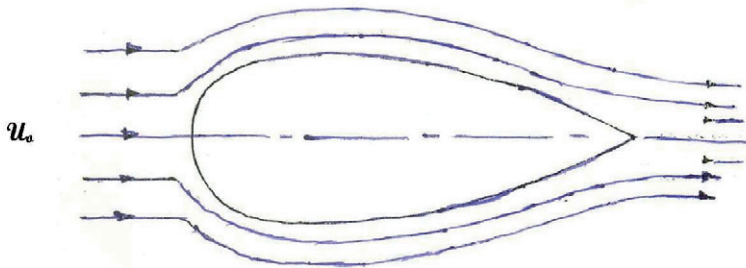
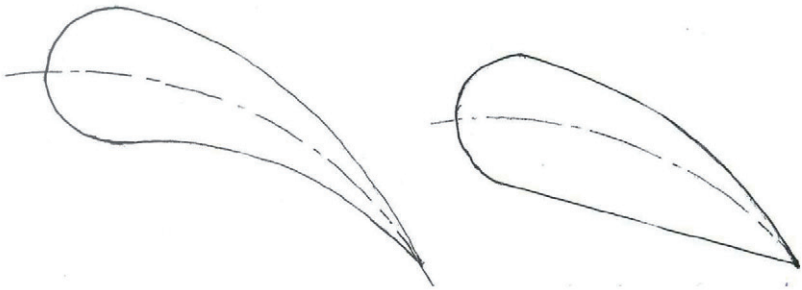


Fig. (2.2) Symmetric Aerofoil



(a) Cambered – cambered aerofoidal Section (b) Straight – cambered aerofoidal Section

Fig. (2.3) Two Types of Aerofoidal Section Profiles

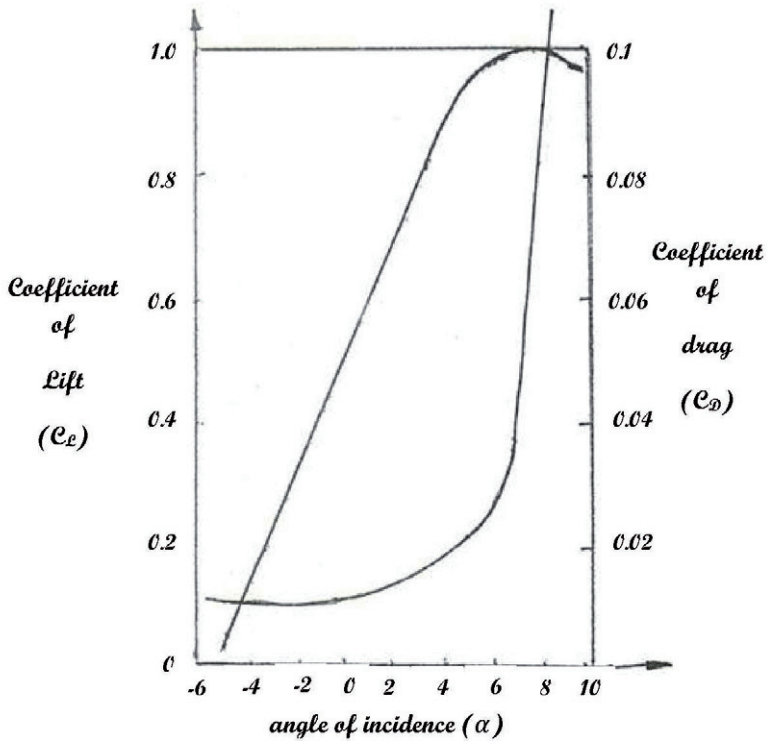


Fig. (2.4) Variation of C_L and C_D with α for A typical Aerofoil

Chapter Three

Model Design and Testing Procedures

3.1 Model Design:

Two types of asymmetric cambered aerofoils blades were selected for testing and compared for efficiency and performance. One type is geometrically similar to that one used in the existing water-current turbine belonging to the Faculty of Engineering and Technology-Atbara, (i.e. straight – cambered aerofoil) and the other type is of different geometric shape (i.e. cambered – cambered aerofoil), which was expected to be to some extent more efficient than the first one. The first type has almost an upper curved surface and a straight lower surface, while the second type has curved profiles on both surfaces.

3.1.1 The Straight – Cambered Aerofoil:

The model is made to a scale of 4:5 of the full size turbine (i.e. Atbara water current turbine). This aerofoil has the following geometrical parameters:

Chord (c) = 160 mm

Maximum thickness (t) = 40 mm

Span (s) = 400 mm

(t/c) Ratio = 25%

(x/c) Ratio = 18%

Position of maximum thickness from the nose (x) = 29 mm.

Percentage camber = 4%

Percentage nose radius = 12.5%

Trailing edge angle = 25 degrees

Fig. (3.1) shows the straight – cambered aerofoil model drawn in full-size dimensions.

3.1.2 The Cambered – Cambered Aerofoil:

The model is made of the same dimensions as that of the straight – cambered

aerofoil. This aerofoil has the following geometrical parameters:

Chord (c) = 160 mm

Maximum thickness (t) = 36 mm

Span (s) = 400 mm

(t/c) Ratio = 22.5%

(x/c) Ratio = 12.5%

Position of maximum thickness from the nose (x) = 20 mm.

Percentage camber = 8.5%

Percentage nose radius = 12.5%

Trailing edge angle = 20 degrees

This aerofoil which is desired to be compared with the straight-cambered aerofoil is shown full-size in fig. (3.2).

3.1.3 Blades Manufacturing:

Two sets of blades were made of ply wood. Each set includes three similar blades; the first set is of a section profile of a straight-cambered aerofoil while the second set is of a cambered – cambered aerofoil. The tip of each blade was rounded so as to decrease the trailing vortices. All blades were painted by a metallic paint where several layers of paint were made in order to prevent water penetration. A piece of mild steel strip with welded nut was bolted to each blade for the purpose of securing the blade to the screw of the boss. A pointer was fixed to the lower end of each blade at the leading edge (i.e. nose) for the purpose of adjusting the angle of incidence, and a set of three protractors is fixed to the boss under the blades so as to adjust the required angle of incidence.

3.1.4 Design and Manufacturing of Chassis and Shaft:

3.1.4.1 The Chassis:

The chassis consists of two parts: one part has two bearing brackets 40mm diameter for holding the shaft while the other part is used for fixing the whole arrangement to the chassis of the already existing water – current turbine at Atbara

River-Nile which is shown in fig. (3.4). The former part is inclined at 38° to the horizontal (i.e. similar to that already existing one), so as to allow the rotor to be completely immersed in water. A 36mm mild steel angle plate is used for manufacturing the whole chassis. Welding, riveting and bolting techniques are used for joining the various pieces of the chassis. Fig. (3.3) shows the basic parts of water current turbine holding mechanism.

3.1.4.2 The Shaft:

It is a hollow shaft 1.2m long and a 30mm diameter made of mild steel. It has a boss made of a circular mild steel disc 100mm diameter and 10mm thickness. This boss is welded rigidly to the shaft and has 3 equi – spaced screws (M10) for holding the blades. At each screw a protractor is fixed by means of a nut and washers. The other end of the shaft is closed by welding a mild steel disc plate on it. The purpose of the protractors and the pointers mentioned in section 3.1.3 is to measure the different angles of incidence required during the test.

3.1.5 The Prony Brake:

A Prony brake is made of mild steel strip 25mm wide and 3mm thick. It has an arm length of 190mm measured from the centre of rotation of the shaft. A spring balance of the range (0–100N) is used in conjunction with the Prony brake to form a torque measuring system. The torque needed to be measured is that transmitted by the shaft. A vertical holder fixed to the inclined part of the chassis is used for holding the spring balance.

A stop watch is used for measuring the rotational speed of the shaft. This method is done by counting the number of revolutions of the shaft in one minute.

A current flow meter type B FM 001 English made is used for measuring the current velocity at equal intervals during test, where several readings are taken and the average value is calculated.

3.2 Testing Procedures:

The procedures which are followed at any reading can be summarized in the

following points:

- a. Raising the immersed rotor outside the water after braking the shaft with the Prony brake device.
- b. Using spanner for adjusting the angle of incidence of the three blades in turn as required.
- c. Lowering the rotor so as to be completely immersed in water and fixing it at this position.
- d. Releasing the Prony brake to liberate the shaft and allow it to rotate about 1 minute approximately before taking the new reading.
- e. Using a stop watch and a tachometer to count the number of revolutions of the shaft during one minute. This will represent the shaft speed in rev/min.
- f. Applying the Prony brake to the shaft until it is completely stopped, and then the spring-balance reading is recorded.
- g. The speed of rotation and the spring balance readings are taken three times per each setting of the angle of incidence, and then the average values are registered.
- h. The reading of the current velocity is taken by the current flow-meter at every setting and then a mean value is recorded.
- i. Repeating the above procedures for each setting of the angle of incidence.

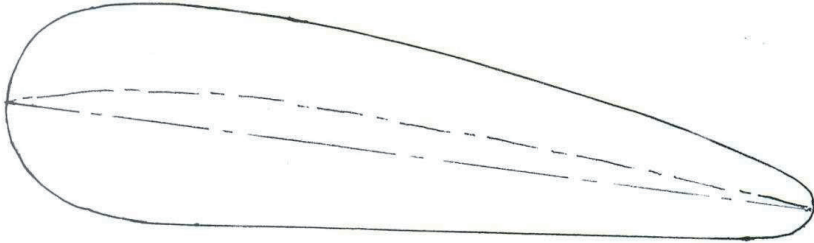


Fig. (3.1) The Straight – Cambered Aerofoil Drawn in Full – Size Dimensions

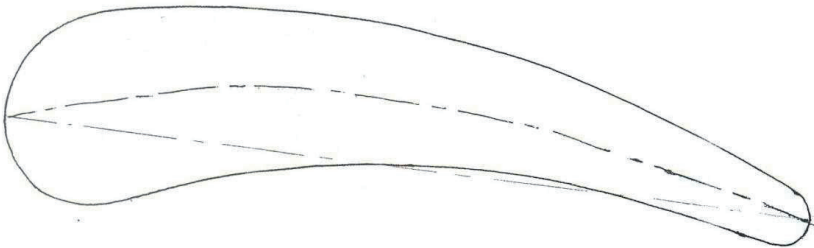
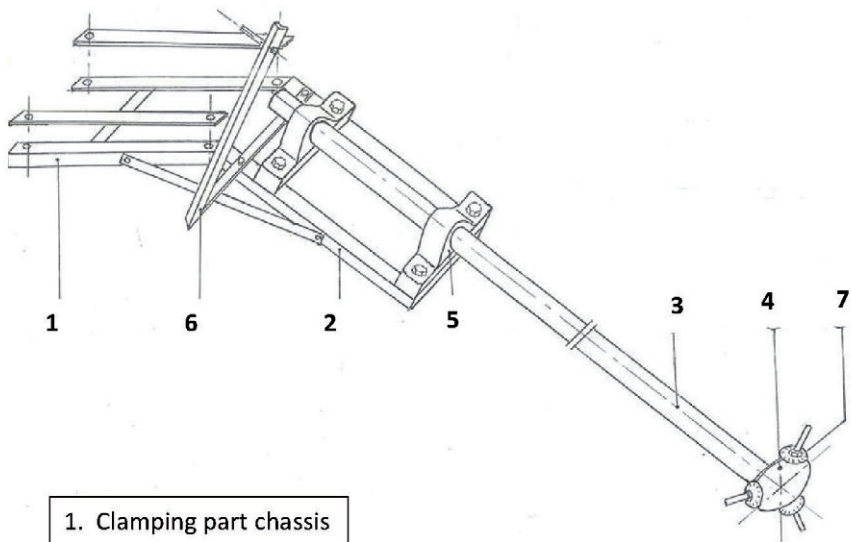
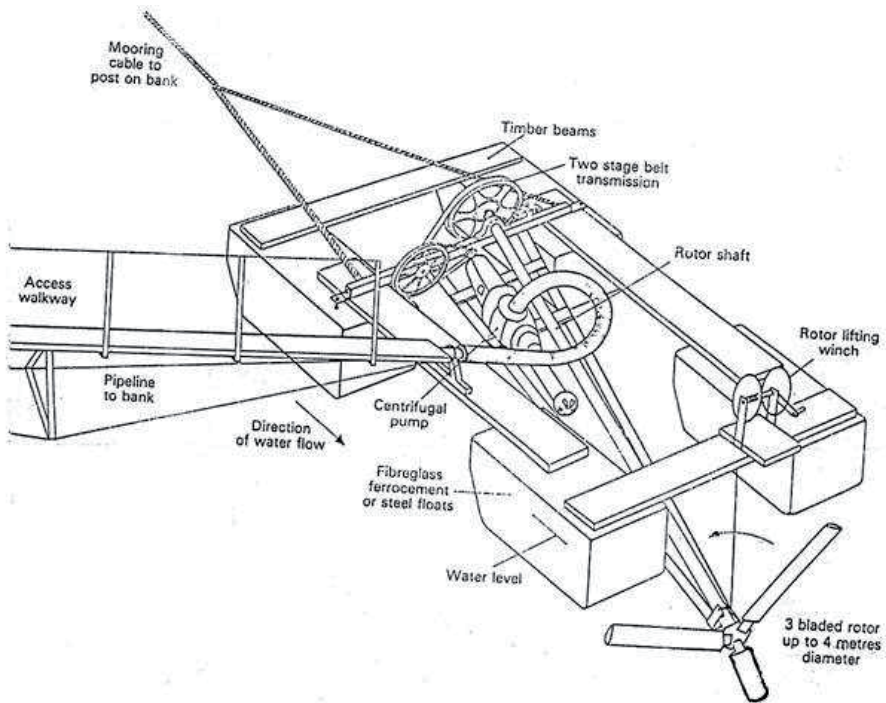


Fig. (3.2) The Cambered – Cambered Aerofoil Drawn in Full – Size Dimensions



- 1. Clamping part chassis
- 2. Inclined part chassis
- 3. Rotor shaft
- 4. Boss
- 5. Bearing bracket
- 6. Spring balance holder
- 7. Protractor

Fig. (3.3) The Holding Mechanism of the Water – Current Turbine Model



**Fig. (3.4) The Full – Size Water Current Turbine
(Atbara Water Current Turbine)**

Chapter Four

Discussion of Results

4.1 Readings:

Tables (4.1) and (4.2) show the readings obtained from testing the straight-cambered aerofoil and cambered – cambered aerofoil respectively.

4.2 Sample of Calculations:

The test readings which are taken from table (4.1) are as follows:

$$\alpha = 60^\circ$$

$$u_o = 1.075 \text{ m/s}$$

$$N = 38 \text{ rev/min}$$

$$\ell = 10^3 \text{ kg/m}^3$$

$$F = 44\text{N}$$

$$c = 0.16 \text{ m}$$

$$r = 0.19 \text{ m}$$

Where;

α = angle of incidence

u_o = average water current speed

N = shaft speed

ℓ = density of water

F = brake force

c = chord length

r = arm length of the Prony brake

From table (4.1) as an example and at an angle of incidence equivalent to 60° , the shaft speed and the brake force are equivalent to 38 RPM and 44 N respectively.

Then, the following quantities can be calculated as follows:

Torque, $T = F.r$

$$= 44 \times 0.19$$

$$= 8.36 \text{ N.m}$$

$$\begin{aligned} \text{Output power, } P_o &= \frac{2\pi TN}{60} \\ &= \frac{2\pi \times 8.36 \times 38}{60} \\ &= 33.27 \text{ W} \end{aligned}$$

$$\begin{aligned} \text{Input power, } P_i &= \frac{1}{2} \ell u_o^3 A \cos 38 \\ &= \frac{1}{2} \times 10^3 (1.075)^3 \frac{\pi}{4} [1^2 - 0.2^2] \cos 38 \\ &= 370 \text{ W (constant value)} \end{aligned}$$

$$\begin{aligned} \text{Efficiency, } \eta &= (P_o/P_i) 100\% \\ &= \frac{33.27}{370} \times 100\% \\ &= 9.00\% \end{aligned}$$

$$\begin{aligned} \text{Maximum dynamic force, } \hat{F}, \text{ per unit span} \\ &= \frac{1}{2} \times \ell u^2 c \\ &= \frac{1}{2} \times 10^3 (1.075)^2 \times 0.16 \\ &= 92 \text{ N (constant value)} \end{aligned}$$

$$\text{Lift force, } L = T/R$$

$$\text{Lift force per unit span, } L' = T/ SR$$

Where;

$$R = \text{mean radius of blade circle} = 0.3 \text{ m}$$

$$S = \text{span} = 0.4 \text{ m}$$

$$\begin{aligned} L' &= 8.36/ (0.4 \times 0.3) \\ &= 70 \text{ N} \end{aligned}$$

$$\begin{aligned} \text{Coefficient of lift, } C_L &= \frac{L'}{\hat{F}} \\ &= \frac{70}{92} \\ &= 0.76 \end{aligned}$$

4.3 Results:

Tables (4.3) and (4.4) show the results calculated from the readings of the straight-cambered aerofoil and the cambered – cambered aerofoil respectively.

4.4 Comments on Graphs and Results Analysis:

4.4.1 Straight – Cambered Aerofoil:

4.4.1.1 Graph of Efficiency against Angle of Incidence:

Fig. (4.1) and table (4.3) show the variation of the efficiency of the turbine model with respect to different angle of incidence ranging between 0 and 96°. It shows that the efficiency increases with the increase of the angle of incidence where it reaches a peak value of 35.7% at 83 degree, and then it decreases sharply with any additional increase in the angle of incidence.

4.4.1.2 Graph of Coefficient of Lift against Angle of Incidence:

Fig. (4.2) and table (4.3) show the variation of coefficient of lift with various angles of incidence ranging from zero to 96°. At an angle of incidence of zero, the coefficient of lift is zero. The coefficient of lift increases with the increase of the angle of incidence where it reaches a maximum value of 1.45 at 83 degree, and then decreases sharply with the increase in the angle of incidence.

4.4.2 Cambered – Cambered Aerofoil:

4.4.2.1 Graph of Efficiency against Angle of Incidence:

Fig. (4.3) and table (4.4) show the variation of the efficiency of the model with different angles of incidence fluctuating between 0 and 96°. The efficiency increases with the increase of the angle of incidence till it reaches a maximum value of 23.6 percent at an angle of 78 degrees, and then decreases sharply until it reaches a zero value at an angle of incidence equivalent to 85 degrees, and then it increases sharply to another peak value of 21 percent at 95 degrees.

4.4.2.2 Graph of Coefficient of Lift against Angle of Incidence:

Fig. (4.4) and table (4.4) show the variation of coefficient of lift with various angles of incidence fluctuating between 0 and 96°. The coefficient of lift is zero at (–6) degrees angle of incidence, and at zero angle of incidence the coefficient of lift is 0.9. The maximum value of the coefficient of lift is 1.13 and occurs at two incidence angles, one at 78 degrees (positive value) and the other at 94 degrees (negative value). Negative coefficient of lift means opposite direction of rotation.

Table (4.1) Readings of the Straight – Cambered Aerofoil

Angle of Incidence (α) (degrees)	Speed (N) (RPM)	Spring -balance Reading (F) (N)
0	0.0	0
2	1.5	4
4	2.5	9
5	2.5	12
6	3.0	15
7	3.0	17
8	3.5	18
9	4.0	19
10	4.0	20
15	6.0	22
20	8.0	25
30	12.0	29
40	19.0	34
50	26.0	38
60	38.0	44
70	52.0	48
80	56.0	53
81	60.0	59
82	65.0	63
83	78.0	85
84	74.0	80
86	70.0	70
88	64.0	50
90	42.0	32
92	36.0	26

94	30.0	23
96	20.0	17

Table (4.2) Readings of the Cambered – Cambered Aerofoil

Angle of Incidence (α) (degrees)	Speed (N) (RPM)	Spring -balance Reading (F) (N)
-6	0.0	0.0
-4	2	12
-2	4	38
0	5	52
2	5	48
4	6	45
5	6	43
6	7	40
7	8	38
8	8	35
9	10	36
10	11	38
15	12	40
20	14	42
30	16	46
40	25	52
50	32	55
60	46	60
70	58	65
80	55	62
81	52	56
82	50	52
83	46	44
84	40	30
86	-28	36
88	-44	54
90	-51	58
92	-54	62
94	-56	66
96	-58	60

Table (4.3) Calculated Results of the Straight – Cambered Aerofoil

(α) (deg.)	Torque (Nm)	Output Power (W)	Efficiency (%)	Lift / unit span (N/m)	Coefficient of Lift (C_L)
0	0.00	0.00	0.00	0.00	0.00
2	0.76	0.12	0.04	6.34	0.07
4	1.71	0.45	0.13	14.25	0.15
5	2.28	0.60	0.17	19.00	0.21
6	2.85	0.90	0.25	23.76	0.26
7	3.23	1.02	0.28	26.92	0.29
8	3.42	1.26	0.34	28.50	0.31
9	3.61	1.52	0.42	30.08	0.33
10	3.80	1.60	0.44	31.66	0.34
15	4.18	2.63	0.72	34.84	0.38
20	4.75	3.98	1.08	39.60	0.43
30	5.51	6.93	1.90	46.00	0.49
40	6.46	12.86	3.48	54.00	0.59
50	7.22	19.66	5.32	60.16	0.65
60	8.36	33.27	9.00	70.00	0.75
70	9.12	49.70	13.43	76.00	0.82
80	10.07	59.06	16.00	83.92	0.91
81	11.21	70.44	19.04	93.42	1.01
82	11.97	81.48	22.02	99.76	1.06
83	16.15	132.00	35.68	134.60	1.45
84	15.20	117.79	31.84	126.66	1.37
86	13.30	97.50	26.35	110.84	1.20
88	9.50	63.67	17.21	79.16	0.86
90	6.08	26.75	7.23	50.66	0.55
92	4.94	18.62	5.03	41.16	0.45
94	4.37	13.73	3.71	36.42	0.39
96	3.23	6.80	1.83	10.77	0.12

Table (4.4) Calculated Results of the Cambered – Cambered Aerofoil

(α) (deg.)	Torque (Nm)	Output Power (W)	Efficiency (%)	Lift /unit span (N/m)	Coefficient of Lift (C_L)
-6	0.00	0.00	0.00	0.00	0.00
-4	2.30	0.48	0.13	19.00	0.21
-2	7.20	3.04	0.82	6.00	0.65
0	9.90	5.20	1.41	82.50	0.90
2	9.10	4.78	1.30	76.00	0.92
4	8.60	5.37	1.45	72.00	0.78
5	8.20	5.13	1.39	68.50	0.74
6	7.60	5.58	1.51	63.50	0.69
7	7.20	6.06	1.64	60.00	0.65
8	6.70	5.58	1.51	56.00	0.60
9	6.80	7.17	1.94	56.50	0.61
10	7.20	8.33	2.25	60.00	0.65
15	7.60	9.55	2.58	63.50	0.69
20	8.00	11.70	3.16	66.50	0.72
30	8.70	14.64	4.00	72.50	0.80
40	9.900	25.90	7.00	82.50	0.90
50	10.45	35.02	9.47	87.00	0.94
60	11.40	54.92	14.85	95.00	1.03
70	12.35	75.01	20.28	103.00	1.12
80	11.78	67.85	18.34	98.00	1.06
81	10.64	58.00	15.68	89.00	0.96
82	9.90	51.73	14.00	82.50	0.90
83	8.36	40.27	10.90	70.00	0.76
84	5.70	23.90	6.46	47.50	0.52
86	-6.84	20.06	5.42	-57.00	-0.61
88	-10.26	47.27	12.78	-85.50	-0.92
90	-11.0-02	58.90	15.92	-92.00	-1.00
92	-11.78	66.61	18.00	-98.00	-1.06
94	-12.54	73.54	19.88	-104.50	-1.13
96	-11.40	69.24	18.71	-95.00	-1.02

Note: Negative Sign means Opposite Direction

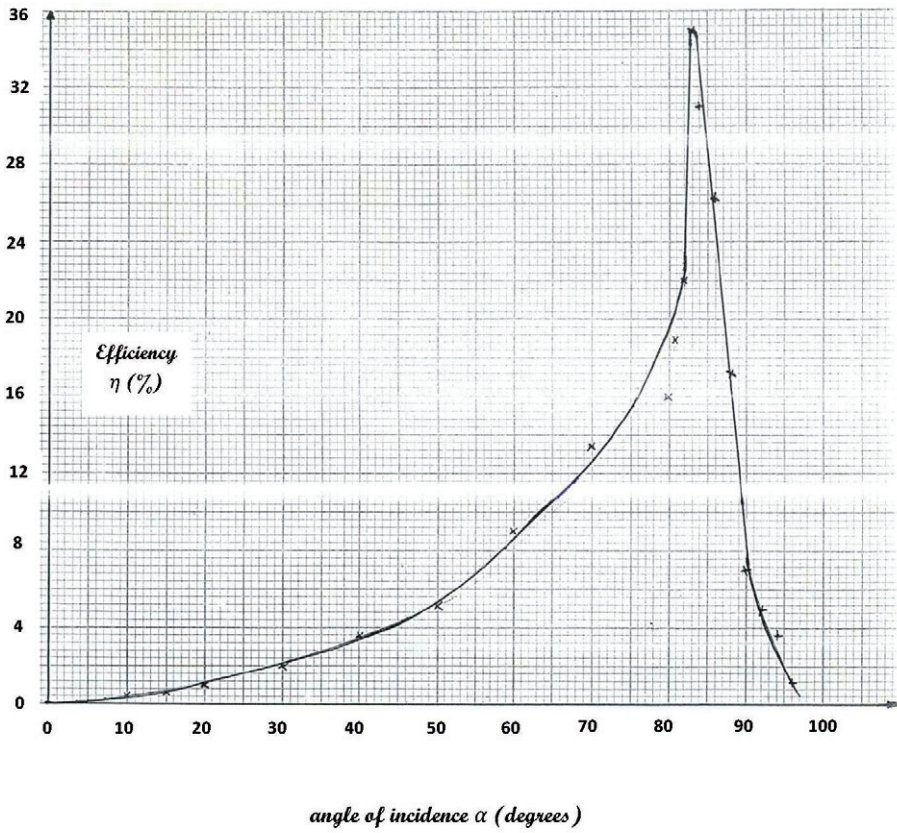


Fig. (4.1) Efficiency against Angle of Incidence of Straight – Cambered Aerofoil

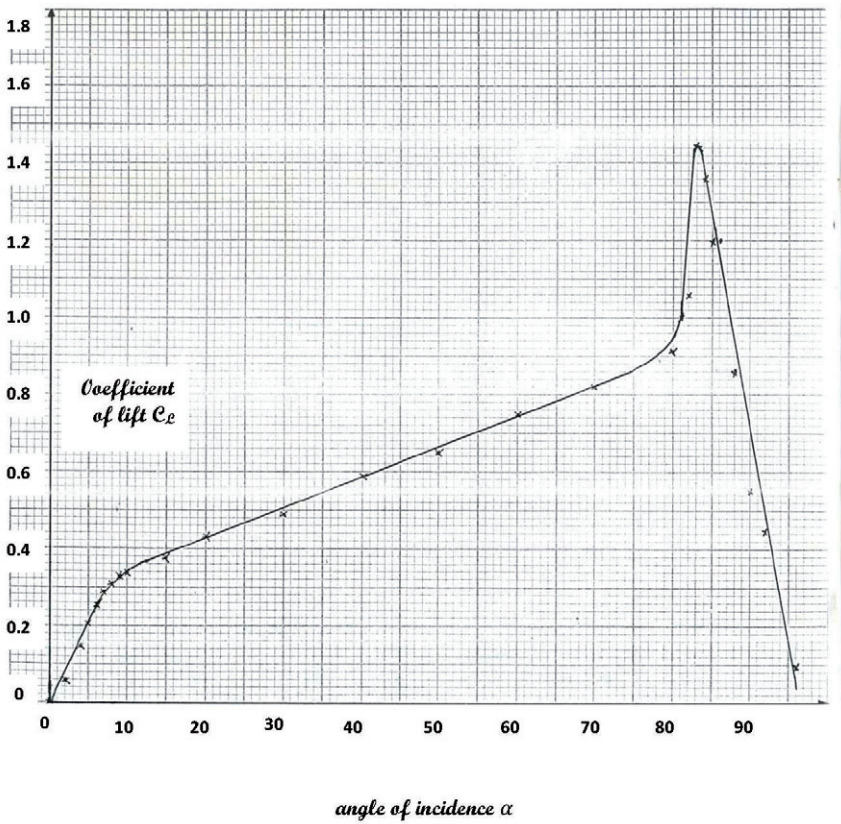


Fig. (4.2) Coefficient of Lift against Angle of Incidence of Straight – Cambered Aerofoil

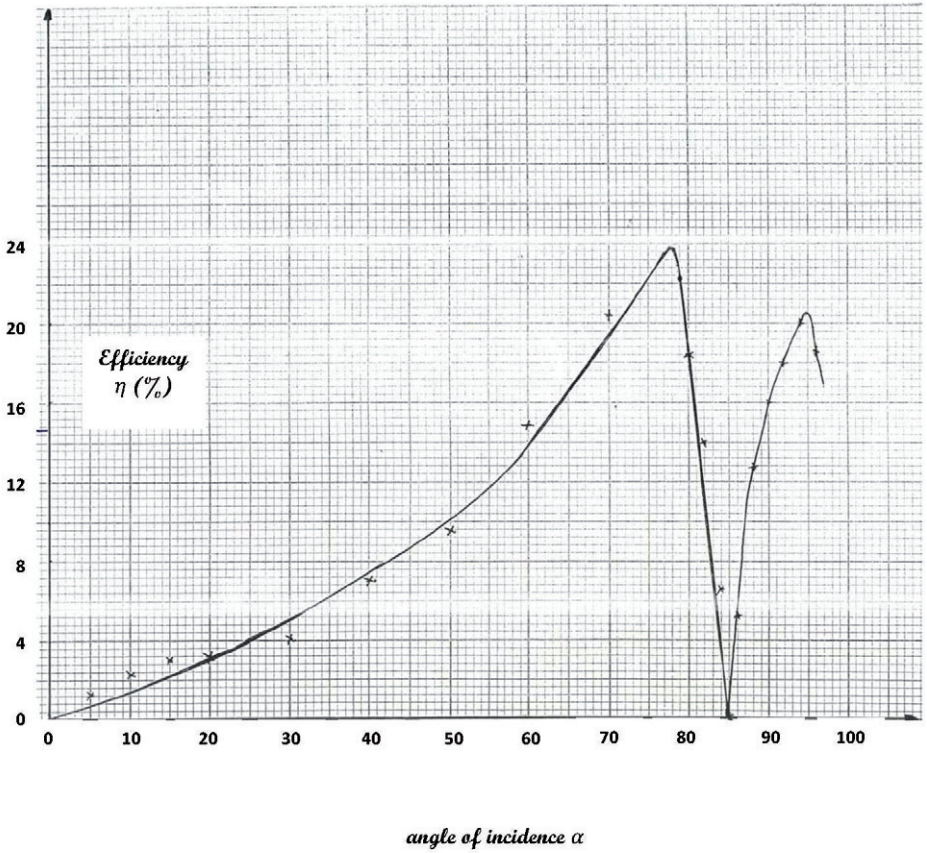


Fig. (4.3) Efficiency against Angle of Incidence of Cambered – Cambered Aerofoil

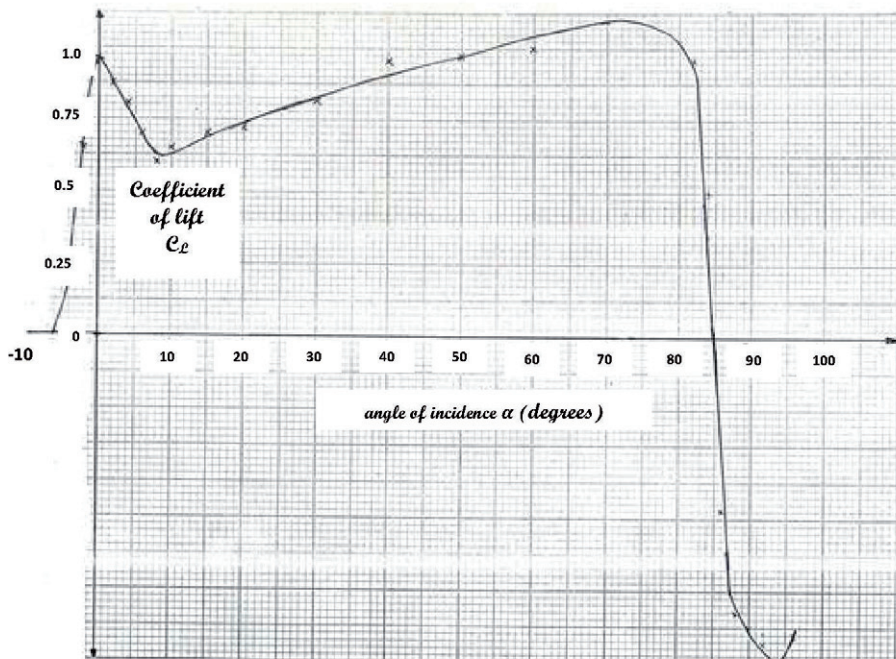


Fig. (4.4) Coefficient of Lift against Angle of Incidence of Cambered – Cambered Aerofoil

Chapter Five

Conclusions and Recommendations

5.1 Conclusions:

The common factor in all rotodynamic machines is that the fluid is fed to the runner or rotating element continuously in such a way that it has a tangential velocity component (or velocity of whirl) about the axis of the shaft as it enters the runner and emerges radially or axially having lost its tangential momentum and exerted a torque on the runner in the process.

In the water-current turbine, the hydraulic energy of the fluid supplied to the machine is converted by three or more blades of aerofoidal section profile into kinetic energy, and this happens because of the high difference in pressure created due to the shape and the setting of a certain angle of attack. This action produces a force on the shaft and a torque on the blade.

It is clear from the readings taken and the corresponding graphs illustrated in chapter four, that the straight-cambered aerofoil blades gives the maximum power (i.e. the product of torque and angular velocity), and this experimental result obtained has rejected the hypothesis that the curved-cambered aerofoil would have given us the best results concerning the maximum power output, and this happens because the separation point moves extremely forward which helps the adverse pressure to build up. The hypothesis is based on the fact that curved surfaces will give high change in momentum according to its profile, but although these results are of trivial benefit in this junction, it creates opportunities for applications other than water-current turbine used for irrigation purposes. The extremely higher torques with lower speeds which have been obtained from the curved-cambered aerofoil can be of great usefulness in other engineering applications that need higher torques (for example grain mills, etc.).

From the results obtained, it is clear that the straight-cambered aerofoil

gives the best results concerning the torque and speed.

5.2 Recommendations:

The water-current turbine machine made in the Faculty of Engineering and Technology- Atbara needs some modifications in its design and consequently the manufacture of some major parts.

It is noticed that the type of transmission used is the one which works with flat belt and pulley system. It has the advantage of less costly, light in weight and easily manufactured and also it is durable and non-corrosive (the pulley is made of aluminium alloy), but it has relatively fair efficiency of transmission (i.e. not more than 75%) in comparison to gear transmission system which has a higher efficiency of 98%. Therefore, it is recommended to use gear transmission system with the necessary anti – corrosion protection needed. Also another advantage of the gearing transmission system is that, there is a possibility of increasing or decreasing the speed through several stages without a remarkable drop in the overall efficiency.

It is also recommended that a compact design of the complete arrangement is required so as to lessen the machine size and consequently the working area. This could be attained by using a vertical shaft instead of a horizontal shaft or an inclined shaft. Consequently, testing of maximum power and efficiency may be carried out on aerofoil blades in the vertical positions which are expected to be greater than that of the inclined shaft. It is also recommended to study the effect of the thickness of the aerofoil section, the span length and chord length to the maximum power output and the overall efficiency of the system. Also the effect of increasing and decreasing the number of blades must be studied.

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